

10.5 Robustness for Parameterized Programs

Motivation: Libraries cannot make assumptions on the number of threads executing their functions.

Goal: Solve robustness for parameterized programs.

Definition (Parameterized programs):

- Syntactically, a parameterized program $P = \{t_1, \dots, t_k\}$ consists of a finite number of threads (like a normal parallel program).
- Semantically, a parameterized program represents a family of parallel programs, so-called instances:
for every vector $I = (n_1, \dots, n_k) \in \mathbb{N}^k$,
instance $P(I)$ has n_i copies of thread t_i .

The parameterized robustness problem is as follows:

Given: A parameterized program P .

Problem: Does $\text{Tr}_{TSO}(P(I)) = \text{Tr}_{SC}(P(I))$ hold
for all instances $P(I)$ of P ?

Approach:

- With instrumentation, instance $P(I)$ is not robust iff there is an attack IT so that $P(I)_A$ reaches a goal configuration.
- Impossible to instrument every instance $P(I)$, infinitely many.
Instead, instrument P directly, turning P into P_A which is now a parameterized program.

Careful:

- ↳ Only one copy of t_A should act as attacker.
- ↳ The remaining copies of t_A have to behave like helpers.
- ↳ Hence, t_A has to be instrumented both, as attacker and as helper.
- ↳ To make sure a single thread becomes the attacker, introduce a flag that is set atomically from 0 to 1 (by the thread acting as attacker).
Atomic instructions like test-and-set can be added to our programming model without harm for the theory.

- Apart from this change $P(I)_A$ and $P_A(I)$ coincide.

Theorem:

If parameterized program P is not robust
 iff there is an attack A so that
 an instance $P_A(I)$ of the parameterized program P_A
 reaches a goal configuration under SC .

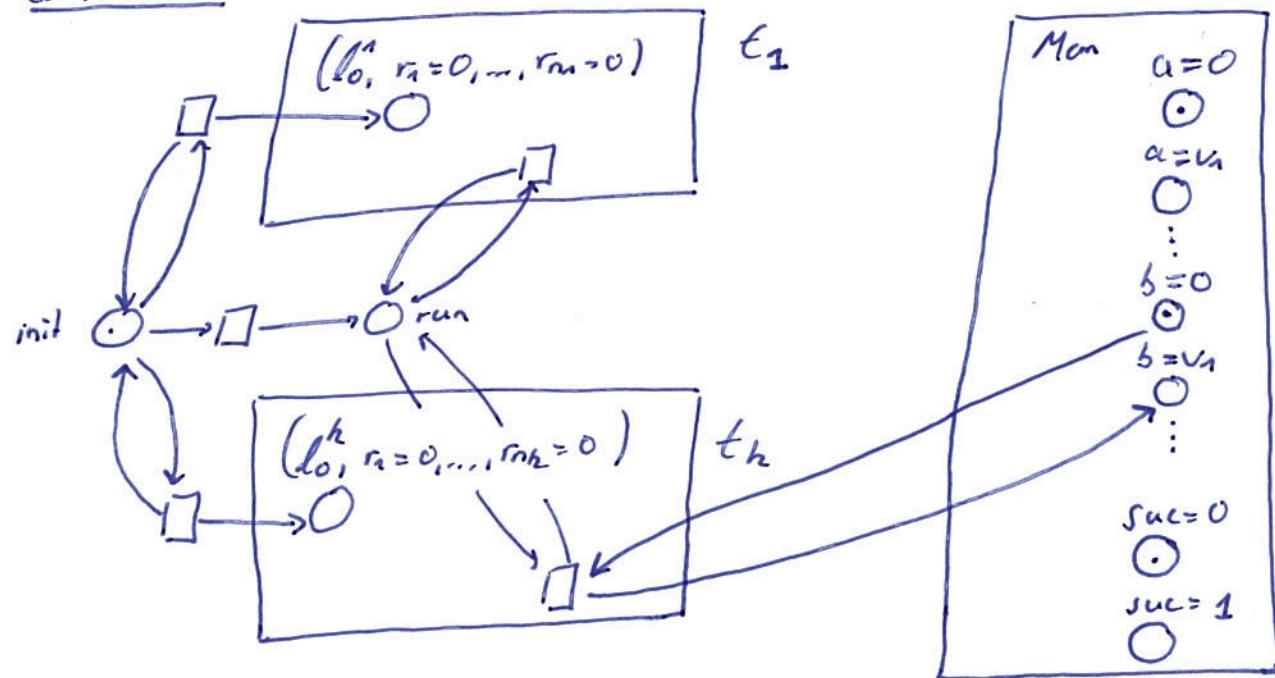
From parameterized programs over finite domains to Rehins:
 Consider parameterized programs over finite domains.

Goal: Show that ⁽¹⁾ reachability of a goal configuration
 in an instance of P_A
 can be formulated as a coverability problem for Rehins.

Idea: Threads never use their identities,
 hence there is no need to track their identities.
 Instead, we count how many instances of each thread
 are in a certain (local) configuration.

The technique is known as counter abstraction

Construction:



Theorem:

Robustness for parametrized programs over finite domains
is decidable in 2EXPSPACE
and EXPSPACE -hard, already in the Boolean case.

Proof:

Coverability for Petri nets is EXPSPACE -complete.

↳ We reduce parametrized robustness
to coverability in an exponentially large Petri net.

This gives a 2EXPSPACE upper bound.

↳ For the lower bound, we reduce coverability
to SC-reachability for parametrized programs
(with atomic test-and-set).

Then hardness of robustness follows like in the non-parametrized case. \square