## Summaries for Context-Free Games

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## Language-Theoretic Verification

## Verification

Verification problem:
Given: Source code of program $P$ and specification $\varphi$.
Question: Does runtime behavior of $P$ satisfy $\varphi$ ?

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Language-theoretic approach:
$\mathcal{L}_{P}=$ possible program executions
$\mathcal{L}_{\varphi}=$ valid executions
Decide: $\mathcal{L}_{P} \subseteq \mathcal{L}_{\varphi}$

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Good: $\mathcal{L}_{\varphi}$ usually easy (regular)
Bad: $\mathcal{L}_{P}$ usually not even context free

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$\mathcal{L}_{P}=$ possible program executions
$\mathcal{L}_{\varphi}=$ valid executions

Good: $\mathcal{L}_{\varphi}$ usually easy (regular)
Bad: $\mathcal{L}_{P}$ usually not even context free
$\checkmark$ Problem is undecidable
$\checkmark$ Need to approximate $\mathcal{L}_{P}$

## Language-theoretic verification

Semantics:

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Lessons in life:
Handle control flow using techniques from automata theory
Handle data using techniques from logic

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Need to combine them
CEGAR loop [Podelski et al. since 2010]

## Counterexample-guided abstraction refinement

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\text { Init } \mathcal{L}_{S}:=\mathcal{L}_{\varphi}
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Init $\mathcal{L}_{S}:=\mathcal{L}_{\varphi}$
$\frac{\downarrow}{\mathcal{L}_{\text {CF }} \subseteq \mathcal{L}_{S} \text { ? }}$

## Counterexample-guided abstraction refinement

$$
\begin{aligned}
& \text { Init } \mathcal{L}_{S}:=\mathcal{L}_{\varphi} \\
& \qquad \\
& \qquad \begin{array}{l}
\text { L} C F \subseteq \mathcal{L}_{S} ?
\end{array} \text { yes } \text { return } P \models \varphi
\end{aligned}
$$

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## Language-Theoretic Synthesis

Synthesis



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Synthesis problem:
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Decide: Is there an instantiation $T @ i$ of $T$ satisfying $\varphi$ ?

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Approach:
Language-theoretic synthesis
CEGAR loop

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Model the control flow of a template as a grammar
Two types of non-determinism

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Model the control flow of a template as a grammar
Two types of non-determinism

## Demonic / Uncontrollable non-determinism

```
proc F()
    if (x == 0)
        G()
    else
        H()
    F }\quad\operatorname{read}(x,0)
        read(x,1)H
```


## Language-theoretic synthesis

Model the control flow of a template as a grammar
Two types of non-determinism

## Demonic / Uncontrollable non-determinism

## Angelic / Controllable

 non-determinismproc F()
if ???
G()
else
H()
$\begin{array}{ll}F \rightarrow \quad & \operatorname{read}(x, 0) G \\ & \operatorname{read}(x, 1) H\end{array}$
$\begin{array}{ll}F \rightarrow & G \\ & \\ & H\end{array}$


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Algorithmically:
Model as a (context-free) two player perfect information game

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Is there a strategy s for player $\square$ to resolve the controllable non-determinism so that

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\mathcal{L}(G @ s) \subseteq \mathcal{L}(A) ?
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From language-theoretic verification to synthesis:
Replace the inclusion check $\mathcal{L}(G) \subseteq \mathcal{L}(A)$ in the CEGAR loop by a strategy synthesis

## Language-theoretic synthesis



Context-Free Games

## Context-free games - Input

## Input:

Context-free grammar with ownership partitioning of the non-terminals

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\begin{array}{ll}
X_{\bigcirc} \rightarrow a Y & \mid \\
Y_{\square} \rightarrow b X &
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\end{array}
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Finite automaton over terminals $T_{G}$


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Vertices: Sentential forms $\vartheta=\left(N_{G} \cup T_{G}\right)^{*}$
Arcs: Left derivations $w X \gamma \Rightarrow_{L} w \eta \gamma$ if $X \rightarrow \eta \in P_{G}$
Ownership: Owner of $w X \gamma$ is the owner of $X$

## Context-free games - Winning conditions

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Inclusion game:
Derive a terminal word $w \in \mathcal{L}(A)$ or infinite derivation
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## Non-Inclusion game:

Derive a terminal word $w \notin \mathcal{L}(A)$ after finitely many steps
$\longrightarrow$ Reachability game

Here:
Consider inclusion game for player prover $\square$
Consider non-inclusion game for player refuter $\bigcirc$

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Stack content represented as a regular language

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## Summaries for context-free games

How to decide which player wins the game?
Fixed-point iteration over a suitable summary domain

Now:

1. Explain \& define domain
2. Explain fixed-point iteration

Formulas over the Transition Monoid

## The tree of plays

How to decide whether refuter can win from a given position?
Consider the tree of plays!


Refuter wins non-inclusion in (ab)* by picking $X \rightarrow \varepsilon$ $Y$ is a winning position for refuter $\bigcirc$

## The tree of plays - Example



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## Formulas

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Tree is usually infinite

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Understand tree as (infinite) positive Boolean formula over words

## Formulas - Example



## Formulas

Remaining problems:

1. Formulas are still infinite
2. Even the set of atomic propositions $T_{G}{ }^{*}$ is infinite

4 Tackle 2. first

## Equivalence relation

Observation 2:
The words are not important - only the state changes matter

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$$

iff

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\begin{gathered}
w \sim_{A} v \\
\text { iff } \quad \forall q, q^{\prime} \in Q:
\end{gathered}
$$

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$$
\begin{aligned}
& \quad w \sim_{A} \vee \\
& \text { iff } \quad \forall q, q^{\prime} \in Q: \quad q \xrightarrow{w} q^{\prime} \quad \text { iff } \quad q \xrightarrow{v} q^{\prime}
\end{aligned}
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\text { iff } & \forall q, q^{\prime} \in Q: \quad q \xrightarrow{w} q^{\prime} \quad \text { iff } \quad q \xrightarrow{v} q^{\prime}
\end{array}
$$

$M_{A}$ is the set of all equivalence classes [ $w$ ] of $\sim_{A}$
$T_{G}{ }^{*}$ is partitioned into equivalence classes of $\sim_{A}$

## Transition monoid

Represent equivalence classes by boxes:

$$
\operatorname{box}(w)=\left\{\left(q, q^{\prime}\right) \in Q \times Q \mid q \xrightarrow{w} q^{\prime}\right\} \in \mathcal{P}(Q \times Q)
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Boxes correspond to procedure summaries for programs (in a precise sense)

## Transition monoid - Example

$$
\operatorname{box}(w)=\left\{\left(q, q^{\prime}\right) \in Q \times Q \mid q \xrightarrow{w} q^{\prime}\right\}
$$



All other boxes represent empty equivalence classes

## Relational composition of boxes

Boxes can be composed using relational composition ;


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Monoids are isomorphic:

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$\left\llcorner\right.$ Up to $\left|M_{A}\right| \leq 2^{|Q|^{2}}$ equivalence classes

## Back to games

Previously: (Infinite) positive Boolean formulas over words

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Down to finitely many atomic propositions

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Remaining problem:
Formulas themselves are infinite

## Formulas - Example



## From infinite to finite formulas

Observation 3:
Every infinite formula over $M_{A}$ is logically equivalent (under suitable evaluation semantics) to some finite formula

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All such functions can be represented by finite formulas
Restrict to finite positive Boolean formulas over $M_{A}$

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## Restrict to finite positive Boolean formulas over $M_{A}$

## Domain:

Finite positive Boolean formulas over $M_{A}$ (up to $\Leftrightarrow$ )
Least element: false
Partial order: Implication $\Rightarrow$

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## Restrict to finite positive Boolean formulas over $M_{A}$

In the example:
Infinite formula: $[\varepsilon] \vee([a b] \vee([a b a b] \vee \ldots))$
Note: $[a b]=[a b a b]=[a b a b a b]=\ldots$
Finite formula: $[\varepsilon] \vee[a b]$

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Finite formula: $[\varepsilon] \vee[a b]$
How to compute these finite formulas in general?

Fixed-Point Iteration

## Fixed point iteration

Problem:
How to compute the formulas?
Fixed-point iteration:
Translate the grammar into a system of equations
Solve using Kleene iteration

## Fixed-point iteration - Example



System of equations
$F_{X}=[a] ; F_{Y} \vee[\varepsilon]$
$F_{Y}=[b] ; F_{X}$

## Fixed-point iteration - Example

Iteration:

| Nr. | $F_{X}$ | $F_{Y}$ |
| :--- | :--- | :--- |

Grammar

$$
\begin{array}{lll}
X_{\bigcirc} \rightarrow a Y & \varepsilon \\
Y_{\square} \rightarrow b X &
\end{array}
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System of equations

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## Fixed-point iteration - Example

Iteration:

## Grammar

| Nr. | $F_{X}$ | $F_{Y}$ |
| ---: | :--- | :--- |
| 0 | false | false |

$$
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$Y_{\square} \rightarrow b X$

| Nr. | $F_{X}$ | $F_{Y}$ |
| ---: | :--- | :--- |
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| 1 | $[\varepsilon]$ | false |

System of equations

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| 3 | $[a b] \vee[\varepsilon]$ | $[b]$ |

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| 4 | $[a b] \vee[\varepsilon]$ | $[b] ;([a b] \vee[\varepsilon])$ |

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$X_{\bigcirc} \rightarrow a Y \quad \mid \varepsilon$
$Y_{\square} \rightarrow b X$

System of equations

$$
\begin{aligned}
& F_{X}=[a] ; F_{Y} \vee[\varepsilon] \\
& F_{Y}=[b] ; F_{X}
\end{aligned}
$$

| Nr. | $F_{X}$ | $F_{Y}$ |
| ---: | :--- | :--- |
| 0 | false | false |
| 1 | $[\varepsilon]$ | false |
| 2 | $[\varepsilon]$ | $[b]=[b] ;[\varepsilon]$ |
| 3 | $[a b] \vee[\varepsilon]$ | $[b]$ |
| 4 | $[a b] \vee[\varepsilon]$ | $[b] ;([a b] \vee[\varepsilon])$ <br> $=[b a b] \vee[b]$ |

## Fixed-point iteration - Example

Iteration:

Grammar
$X_{\bigcirc} \rightarrow a Y \quad \mid \varepsilon$
$Y_{\square} \rightarrow b X$

System of equations

$$
\begin{aligned}
& F_{X}=[a] ; F_{Y} \vee[\varepsilon] \\
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| 3 | $[a b] \vee[\varepsilon]$ | $[b]$ |
| 4 | $[a b] \vee[\varepsilon]$ | $[b] ;([a b] \vee[\varepsilon])$ <br> $=[b a b] \vee[b]$ <br>  |
|  | e |  |

Winning Regions

## Rejecting

Define the evaluation $\varphi$ by

$$
\begin{aligned}
\varphi: M_{A} & \rightarrow\{0,1\} \\
{[w] } & \mapsto \begin{cases}1 & \left(q_{0}, q_{f}\right) \notin \operatorname{box}(w) \text { for all } q_{f} \in Q_{f} \\
0 & \text { else }\end{cases}
\end{aligned}
$$

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0 & \text { else }\end{cases} \\
& \varphi([w])=1 \quad \text { iff } \quad w \notin \mathcal{L}(A)
\end{aligned}
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$\varphi([b])=1 \quad \varphi([a b])=0$

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\end{aligned}
$$

$\varphi([w])=1 \quad$ iff $\quad w \notin \mathcal{L}(A) \quad$ iff $\quad[w] \subseteq \overline{\mathcal{L}(A)}$

$\varphi([\varepsilon])=0 \quad \varphi([b])=1 \quad \varphi([a b])=0$

Sentential form $\alpha \in \vartheta$ is called rejecting if $\varphi\left(F_{\alpha}\right)=1$

## Winning region of prover

## Theorem

The set of non-rejecting positions

$$
W \subseteq=\left\{\alpha \in \vartheta \mid \varphi\left(F_{\alpha}\right)=0\right\}
$$

is the winning region of prover $\square$ for the inclusion game.

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Show: If the current position is non-rejecting and it is the turn of
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(2) Refuter: All moves go to non-rejecting positions.

Since the inclusion game is a safety game, staying in $W \subseteq$ suffices.

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In the example, starting from $X$ :
Both [ab], $[\varepsilon]$ contain $\left(q_{0}, q_{0}\right)$

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$$

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In the example, starting from $X$ :

$$
\begin{gathered}
\text { Both [ab], [ } \varepsilon \text { ] contain }\left(q_{0}, q_{0}\right) \\
\qquad \varphi([a b])=0, \varphi([\varepsilon])=0
\end{gathered}
$$

## Winning region of prover

## Theorem

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& \qquad \varphi([a b])=0, \varphi([\varepsilon])=0 \\
& \qquad \varphi\left(F_{X}\right)=\varphi([a b] \vee[\varepsilon])=0
\end{aligned}
$$

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## Theorem

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W \subseteq=\left\{\alpha \in \vartheta \mid \varphi\left(F_{\alpha}\right)=0\right\}
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In the example, starting from $X$ :

$$
\begin{aligned}
& \text { Both [ab], [ } \varepsilon \text { ] contain }\left(q_{0}, q_{0}\right) \\
& \qquad \varphi([a b])=0, \varphi([\varepsilon])=0 \\
& \leftrightarrows \varphi\left(F_{X}\right)=\varphi([a b] \vee[\varepsilon])=0 \\
& \leftrightarrows X \text { is non-rejecting }
\end{aligned}
$$

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In the example, starting from $X$ :
Both [ab], [ $\varepsilon$ ] contain ( $q_{0}, q_{0}$ )
$\bigsqcup^{4} \varphi([a b])=0, \varphi([\varepsilon])=0$
$\rightarrow \varphi\left(F_{X}\right)=\varphi([a b] \vee[\varepsilon])=0$
$\bigsqcup X$ is non-rejecting
Indeed, prover wins inclusion from $X$

## Winning region of refuter

## Theorem

## The set of rejecting positions

$$
W^{\notin}=\left\{\alpha \in \vartheta \mid \varphi\left(F_{\alpha}\right)=1\right\}
$$

is the winning region of refuter $\bigcirc$ for the non-inclusion game.

## Winning region of refuter

## Theorem

The set of rejecting positions

$$
W^{\not \subset}=\left\{\alpha \in \vartheta \mid \varphi\left(F_{\alpha}\right)=1\right\}
$$

is the winning region of refuter $\bigcirc$ for the non-inclusion game.

## Proof

Position $w \in \mathcal{L}(A)$ has formula $F_{w}=[w]$ with $\varphi([w])=0$

## Winning region of refuter

## Theorem

The set of rejecting positions

$$
W^{\mathbb{E}}=\left\{\alpha \in \vartheta \mid \varphi\left(F_{\alpha}\right)=1\right\}
$$

is the winning region of refuter $\bigcirc$ for the non-inclusion game.

## Proof

Position $w \in \mathcal{L}(A)$ has formula $F_{w}=[w]$ with $\varphi([w])=0$
$\Rightarrow \mathcal{L}(A) \cap W \notin=\emptyset$

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Position $w \in \mathcal{L}(A)$ has formula $F_{w}=[w]$ with $\varphi([w])=0$

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Show: If the current position is rejecting and it is the turn of

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Show: If the current position is rejecting and it is the turn of
(1) Refuter: There is a move to a rejecting position, (2) Prover: All moves go to rejecting positions.

Not sufficient to win reachability game, need to minimize distance to $\overline{\mathcal{L}(A)}$ in every step.

## Winning region of refuter

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In the example, starting from $Y$ :
[b] does not contain $\left(q_{0}, q_{0}\right)$

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In the example, starting from $Y$ :

$$
\begin{gathered}
{[b] \text { does not contain }\left(q_{0}, q_{0}\right)} \\
\zeta \varphi\left(F_{Y}\right)=\varphi([b])=1
\end{gathered}
$$

## Winning region of refuter

## Theorem

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In the example, starting from $Y$ :
[b] does not contain $\left(q_{0}, q_{0}\right)$
$\iota^{\varphi}\left(F_{Y}\right)=\varphi([b])=1$
$\rightarrow Y$ is rejecting

## Winning region of refuter

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$\rightarrow Y$ is rejecting
Indeed, refuter wins non-inclusion from $Y$

Composition

## Composition

How to define the composition operator ; that replaces concatenation. in the system of equations?

## Composition

Plays from XY decompose:


## Composition

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## Composition

Plays from $X Y$ decompose:


## Composition



Complexity \& Performance

## Algorithm

Given: Game $G, A$ and initial position $\alpha$
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F=\operatorname{rhs}(F)
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Compose solutions $F_{X}$ for non-terminals to obtain the solutions for all sentential forms $\alpha=\alpha_{1} \ldots \alpha_{k} \in \vartheta: F_{\alpha}=F_{\alpha_{1}} ; \ldots ; F_{\alpha_{k}}$

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Compose solutions $F_{X}$ for non-terminals to obtain the solutions for all sentential forms $\alpha=\alpha_{1} \ldots \alpha_{k} \in \vartheta: F_{\alpha}=F_{\alpha_{1}} ; \ldots ; F_{\alpha_{k}}$

Solve system once and decide game for any position $\alpha$

## Complexity

Theorem

1. Deciding non-inclusion games is 2EXPTIME-complete.

## Complexity

## Theorem

1. Deciding non-inclusion games is 2EXPTIME-complete.
2. The algorithm solves non-inclusion games in

$$
\mathcal{O}\left(|G|^{2} \cdot 2^{2^{|Q|^{c_{1}}}}+|\alpha| \cdot 2^{2^{|Q|^{C_{2}}}}\right)
$$

where $c_{1}, c_{2} \in \mathbb{N}$ are constants.

## Complexity

## Theorem

1. Deciding non-inclusion games is 2EXPTIME-complete.
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where $c_{1}, c_{2} \in \mathbb{N}$ are constants.
3. Hardness by reduction from acceptance in alternating Turing machines with exponential space.

## Related Work

Cachat [C02]:

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Consider pushdown system with ownership partitioning of control states

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Can one player enforce a configuration such that the stack content is accepted by an alternating finite automaton (AFA)?

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Solve by saturating the transitions of the AFA

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Saturated AFA accepts the winning region

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## EXPTIME

4 Our game can be reduced to Cachat

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## EXPTIME

$\hookrightarrow$ Similar technique can be applied to our problem

## Related Work

Muscholl, Schwentick, Segoufin [MSS05]:

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Can one player enforce a sentential form in a regular language over $N_{G} \cup T_{G}$ ?

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Similar to our game

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Undecidable
2EXPTIME for left-to-right strategies
Similar to our game
Hardness proof carries over

## Performance

Comparison of 2EXPTIME algorithms:

| Input | Computation |
| :---: | :---: |

Our algorithm

| System of equations | $P$ | Fixed-point iteration | 2EXP |
| ---: | :---: | :---: | :---: |

Reduction to Cachat [C02]

| Determinized automaton | EXP | Saturation | EXP |
| :---: | :---: | :---: | :---: |
| Idea of Walukiewicz [W01] |  |  |  |
| Finite reachability game | 2 EXP | Saturation | P |

guaranteed blow-up
may be lucky

## Performance

We have implemented and compared:
Our algorithm with naive Kleene iteration
Our algorithm with worklist-based Kleene iteration
Reduction to Cachat's pushdown games

Problems with Cachat's algorithm:
Automaton $A$ needs to be determinized
$\rightarrow$ Guaranteed blow-up
Algorithmic tricks for Cachat (worklist, ...) not suitable for the instances generated by the reduction

## Performance

|  | naive Kleene |  | worklist Kleene |  | Cachat |  |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $\|Q\| /\|N\| /\|T\|$ | avg. time | \% timeout | avg. time | \% timeout | avg. time | \% timeout |
| $5 / 5 / 5$ | 65.2 | 2 | 0.8 | 0 | 94.7 | 0 |
| $5 / 5 / 10$ | 5.4 | 4 | 7.4 | 0 | 701.7 | 0 |
| $5 / 10 / 5$ | 13.9 | 0 | 0.3 | 0 | 375.7 | 0 |
| $5 / 5 / 15$ | 6.0 | 0 | 1.1 | 0 | 1618.6 | 0 |
| $5 / 10 / 10$ | 32.0 | 2 | 122.1 | 0 | 2214.4 | 0 |
| $5 / 15 / 5$ | 44.5 | 0 | 0.2 | 0 | 620.7 | 0 |
| $5 / 5 / 20$ | 3.4 | 0 | 1.4 | 0 | 3434.6 | 4 |
| $5 / 10 / 15$ | 217.7 | 0 | 7.4 | 0 | 5263.0 | 16 |
| $10 / 5 / 5$ | 8.8 | 2 | 0.6 | 0 | 2737.8 | 2 |
| $10 / 5 / 10$ | 9.0 | 6 | 69.8 | 0 | 6484.9 | 66 |
| $15 / 5 / 5$ | 30.7 | 0 | 0.2 | 0 | 5442.4 | 52 |
| $10 / 10 / 5$ | 9.7 | 0 | 0.2 | 0 | 7702.1 | 92 |
| $10 / 15 / 15$ | 252.3 | 0 | 1.9 | 0 | $n / a$ | 100 |
| $10 / 15 / 20$ | 12.9 | 0 | 1.8 | 0 | $n / a$ | 100 |

Experiments executed on $77-6700 \mathrm{~K}, 4 \mathrm{GHz}$, times in milliseconds, timeout 10 seconds

Future Work

## Future work

Liveness synthesis (infinite words)

## Future work

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Synthesis for systems with branching behavior (trees)

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Applications in hardware synthesis
Solver technology for systems of equations (Newton iteration)

## Questions?

