

10. Pushdown Automata and Context-free Languages

Goal: Develop an automata-theoretic understanding of context-free languages.

Motivation:
• Will make it easier to show some closure properties
• Needed for parsing.

10.1 Pushdown Automata

Goal: • Introduce a new computational model:

- finite automata that have access to a stack.
- Can store an unbounded amount of information about the history of the computation, but access this information only in a very restricted way (last-in, first-out).

Definition (Syntax of a pushdown automaton):

A (non-deterministic) pushdown automaton (NPDFA)

is a tuple $M = (Q, \Sigma, \Gamma, q_0, \delta, Q_f)$ with

- Q a finite set of states (also called control states), $q_0 \in Q$ the initial state, and $Q_f \subseteq Q$ the set of final states,
- Σ a (finite) input alphabet (alphabets are always finite),
- Γ a (finite) stack alphabet,
- $\delta \subseteq Q \times (\Sigma \cup \{\epsilon\}) \times (\Gamma \cup \{\epsilon\}) \times \Gamma^* \times Q$ a finite set of transitions.

To define the behavior of a PDFA, its semantics, we need the notion of a configuration, the state of the PDA at runtime.

- The configuration should contain
- the current control state and
 - the current stack content.

Definition (Semantics of a pushdown automaton):

Let $M = (Q, \Sigma, \Gamma, q_0, \delta, Q_f)$ be a PDA.

• The set of configurations of M is $Q \times \Gamma^*$.

The initial configuration is (q_0, ϵ) .

A configuration is final (or accepting)

if it is of the form $(q_f, w) \in Q_f \times \Gamma^*$.

• The labelled transition relation among configurations

$$\rightarrow_M \subseteq (Q \times \Gamma^*) \times \Sigma \times (Q \times \Gamma^*)$$

is defined by

$$(q_1, w_1) \xrightarrow{a} (q_2, w_2), \text{ if } q_1 \xrightarrow{a, v_1/v_2} q_2 \in \delta \text{ (this is the tuple } (q_1, a, v_1, v_2, q_2))$$

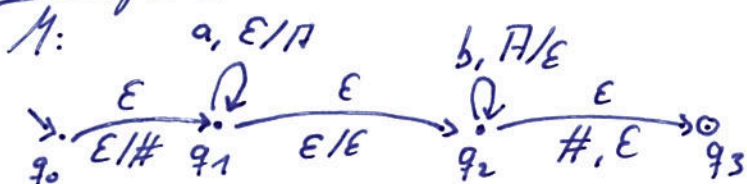
and $w_1 = w \cdot v_1$
and $w_2 = w \cdot v_2$ for some $w \in \Gamma^*$.

We generalize the labelled transition relation to words from Σ^* in the expected way.

• The language of M is

$$L(M) := \{w \in \Sigma^* \mid (q_0, \epsilon) \xrightarrow{w} (q_f, u) \in Q_f \times \Gamma^*\}$$

Example:



$$L(M) = \{a^n b^n \mid n \in \mathbb{N}\}$$

Note:

if PDA M induces an infinite-state automaton

$$\bar{M} := (Q \times T^*, \Sigma, (q_0, \epsilon), \rightarrow_M, Q_f \times T^*)$$

and $L(M) = L(\bar{M})$

(where the language of an infinite-state automaton is defined like for NFAs).

Remark:

There are alternative definitions of PDAs in the literature.

(1) A common alternative is to define acceptance by reaching the empty stack.

In this case, the PDA is a tuple $M = (Q, \Sigma, T, q_0, \#, \delta)$ with $\# \in T$ a symbol that is on the stack initially.

(2) In both models (acceptance via final states and via empty stack), we may assume that transitions

- always pop an element and
- push at most two elements.

For the former restriction, we have to require to start with an initial stack symbol also when accepting with final states.

Theorem:

The alternative definitions accept the same languages as PDAs.

Proof (Sketch):

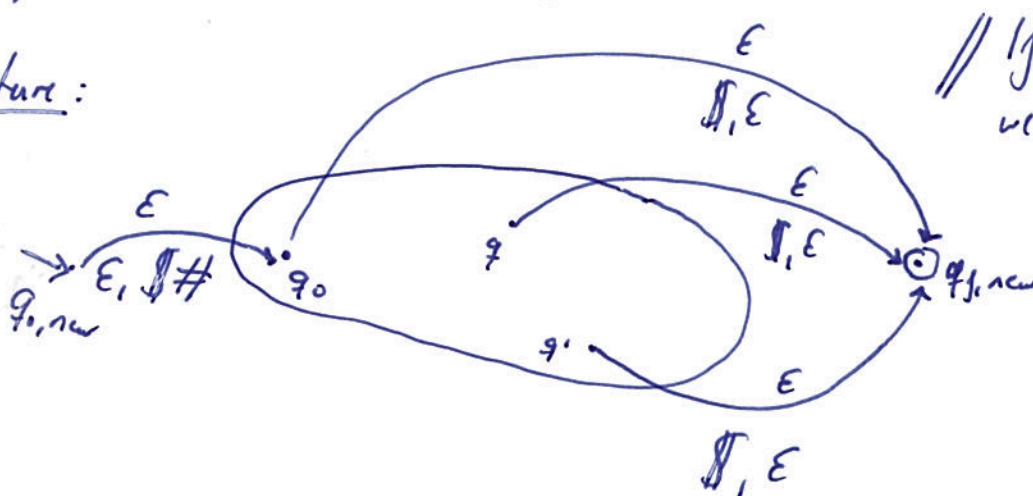
- To mimic empty stack acceptance with our definition,
- let $\#$ be the distinguished initial stack symbol.

- We introduce
- a new initial state,
 - a new final state, and
 - a new bottom of stack symbol $\$$.

We introduce transitions that

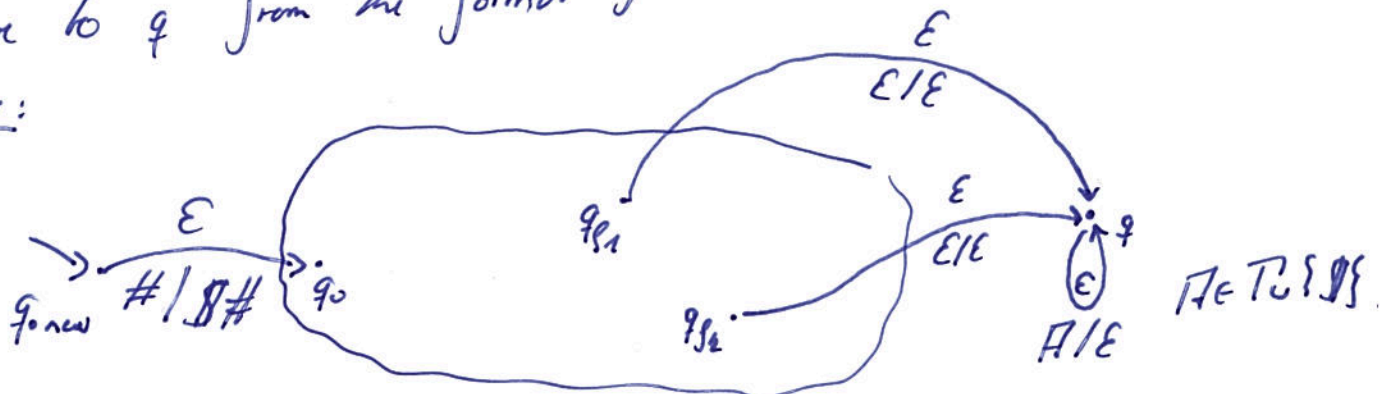
- initially establish the bottom of stack $\$$
- the symbol is never removed except in the last step that takes the PDA from any state to the new final state.

Picture:



- To mimic acceptance with a final state with empty stack, add a new bottom of stack symbol $\$$ so that the stack is not accidentally emptied. Moreover, add a new state q_f in which to empty the stack. Move to q_f from the former final states.

Picture:



• The remaining equivalences can be solved as homework.

10.2 Equivalence with Context-Free Languages

Goal: Show that the languages accepted by PDAs are precisely (coincide with) the context-free languages.

We establish the two directions separately.

Theorem:

If L is context-free, then there is a PDA M with $L = L(M)$.

Idea:

- Mimic the left-derivation relation \Rightarrow_L using the stack.
- We give an elegant proof that makes use of Greibach's normal form.
- The normalization step can be avoided.

Proof:

Let $L = L(G)$ with $G = (N, \Sigma, P, S)$ a context-free grammar.

Assume the grammar is in Greibach normal form so that the productions are

$A \rightarrow a B_1 \dots B_k$ and potentially $S \rightarrow \epsilon$.

We construct an equivalent PDA M that accepts with empty stack.

Interestingly, M has only one state.

The definition is

$M := (\{q\}, \Sigma, \underbrace{N}_{\text{stack alphabet}}, q, \underbrace{S}_{\text{initial stack content}}, \delta)$

For every production $A \rightarrow a B_1 \dots B_k$

there is a transition $q \xrightarrow{a} q$.

So we read letter a from the input,
read A from the top-of-stack, and
write $B_1 \dots B_k$ to the top-of-stack.

Similarly, $S \rightarrow \epsilon$ yields $q \xrightarrow{S/\epsilon} q$.

Claim: $L(M) = L(G)$. □

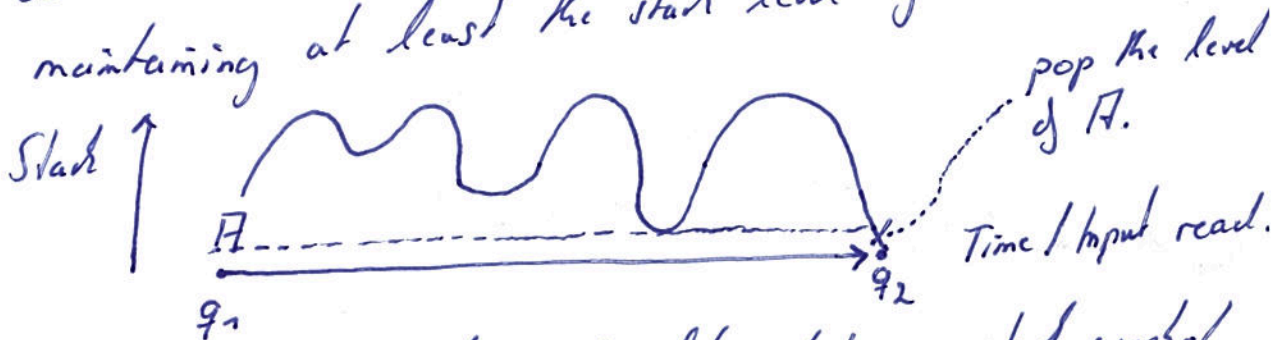
Discussion:

- One can give a similar construction that does not rely on Greibach normal form. Doing this is a good exercise.
- The benefit of the above construction is that we definitely read a letter from the input word with every step. So we can check in NP whether a given word is accepted.

Theorem:

Every language $L(M)$ of a PDA M is context-free.

Idea: • We guess the changes in the control state of the PDA, say from q_1 to q_2 (potentially far away), that can be obtained from a stack symbol A while maintaining at least the stack level of A .



- Guessing the state changes that can be obtained from a stack symbol means we use non-terminals of the form (q_1, A, q_2) .

Proof:

Consider $L(M)$ with $M = (Q, \Sigma, T, q_0, \#, \delta)$ accepting with empty stack.

We assume $\delta \subseteq Q \times (\Sigma \cup \{\epsilon\}) \times T^* \times T^* \times Q$,

so we definitely read a stack symbol in every transition.

We define the grammar to be

$$G := ((Q \times T \times Q) \cup \{S\}, \Sigma, P, S)$$

with

$$P := \{ S \rightarrow (q_0, \#, q) \mid q \in Q \}$$

$$\cup \{ (q, A, q') \rightarrow a. (q'', B_1, q_1) \dots (q_{m-1}, B_m, q') \mid$$

$q_1, \dots, q_{m-1} \in Q$ (m may be 0) and

$$q \xrightarrow[A/B_1 \dots B_m]{a} q'' \text{ with } a \in \Sigma \cup \{\epsilon\} \}.$$

Claim: $L(M) = L(G)$. □

Putting the results together, we obtain an interesting observation about the role of control states in pushdown automata.

Corollary:

For every PDA M , there is a PDA M' that only has one control state and satisfies $L(M) = L(M')$.

(*) Rephrasing the idea of the construction:

Non-terminal (q_1, A, q_2) generates $w \in \Sigma^*$ iff upon input w and with initial stack symbol A ,

\rightarrow M moves from q_1 to q_2 and ends with an empty stack.